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ON THE MEAN CURVATURE OF A DEVELOPABLE TIME-LIKE RULED SURFACE AT THE MOTION OF SPACE WITH ONE PARAMETER  $L/L'$  IN  $R_1^3$

Abstract

*In this study, the integral invariants of a time-like ruled surface are introduced. Furthermore, the mean of a developable time-like ruled surface in this space is calculated in terms of its development invariants.*

1. Introduction.

A surface in the 3-dimensional Minkowski space  $R_1^3 = (R_1^3, dx^2 + dy^2 - dz^2)$  is called a time-like surface if the induced metric on the surface is a Lorentz metric [1]. A ruled surface is a surface swept out by a straight line  $X$  moving along a curve  $\alpha$ . The various positions of the generating line  $X$  are called the ruling of the surface. Such a surface, thus, has a parameterization in ruled form as follows,

$$\varphi(s, v) = \alpha(s) + vX(s). \tag{1.1}$$

We call  $\alpha$  to be the base curve, and  $X$  to be director curve. If the tangent plane is constant along a fixed ruling, then the ruled surface is called a developable surface. The remaining ruled surface are called skew surfaces [6]. If there exists a common perpendicular to two preceding ruling in the skew surface, then the foot of the common perpendicular on the main ruling is called a central point. The locus of the central points is called the curve of striction.

The time-like ruled surface  $M$  is given by the parameterization

$$\begin{aligned} \varphi: I \times R &\rightarrow R_1^3, \\ (s, v) &\rightarrow \varphi(s, v) = \alpha(s) + vX(s) \end{aligned} \tag{1.2}$$

in  $R_1^3$ , where  $\alpha: R \rightarrow R_1^3$  is a differentiable space-like curve parameterized by its arc-length in  $R_1^3$  ( $\langle \alpha'(s), \alpha'(s) \rangle = 1$ ) and  $X(s)$  is the director vector of the director curve such that  $X$  is orthogonal to the tangent vector field  $T$  of the base curve  $\alpha$ .  $\{T, \bar{N}, X\}$  is an orthogonal frame field along  $\alpha$  in  $R_1^3$ , where  $\bar{N}$  is the normal vector field of  $M$  along  $\alpha$ .  $\bar{N}$  and  $T$  are space-like and  $X$  is time-like

$$\langle T, T \rangle = \langle \bar{N}, \bar{N} \rangle = 1, \quad \langle X, X \rangle = -1. \tag{1.3}$$

The curve of striction of a skew time-like surface is given by

$$\bar{\alpha}(s) = \alpha(s) - \frac{\langle \frac{d\alpha}{ds}, \frac{dX}{ds} \rangle}{\langle \frac{dX}{ds}, \frac{dX}{ds} \rangle} X(s) \tag{1.4}$$

$\bar{\alpha}(s)$  is a space-like curve [6]. Let  $P_x$  be distribution parameter of time-like ruled surface, then

$$P_x = \frac{\det \left[ \frac{d\alpha}{ds}, X, \frac{dX}{ds} \right]}{\langle \frac{dX}{ds}, \frac{dX}{ds} \rangle}. \tag{1.5}$$

**Lemma 1.** *The time-like ruled surface  $\varphi(s, v)$  is developable iff the parameter of distribution  $P_x$  is equal zero. That is,*

$$\det \left[ \frac{d\alpha}{ds}, X, \frac{dX}{ds} \right] = 0, [3]. \quad (1.6)$$

## 2. The Frenet vectors, one parameter spatial motion and integral invariants.

If the principle vector field  $N$  of a space-like curve  $\alpha(s)$  is space-like and the binormal vector field  $B$  is time-like, then we have following Frenet formula along  $\alpha(s)$

$$\begin{aligned} D_T T &= k_1 N, \\ D_T N &= -k_1 T + k_2 B, \\ D_T B &= k_2 N \end{aligned} \quad (2.1)$$

[2, 6].

Let  $\alpha: I \rightarrow R_1^3$  be a space-like curve and  $\{T, N, B\}$  be Frenet vector, where  $T, N$  and  $B$  are tangent, principle normal and binormal vectors of the curve, respectively.  $B$  is time-like,  $T$  and  $N$  are space-like vectors.

The two coordinate systems  $\{0; T, N, B\}$  and  $\{O'; e_1, e_2, e_3\}$  are orthogonal coordinate systems in  $R_1^3$  which represent the moving space  $L$  and the fixed space  $L'$ , respectively. Let us express the displacements  $(L/L')$  of  $H$  with respect to  $L'$ . During the one parameter spatial motion  $H/H'$ , each fixed line  $X$  of the moving space  $H$ , generates, in generally, a time-like ruled surface in the fixed space  $L'$ .

**Definition 2.1.** *The vector which is determined by the curvilinear integral along the given curve  $\alpha$  of Pfaff vector  $w$  in the motion of  $L/L'$  as,*

$$D = \int w \quad (2.2)$$

is called the Steiner Rotation vector of motion  $L/L'$  and the vector

$$V = \int dx \quad (2.3)$$

is called the Steiner Transition Vector.

**Definition 2.2.** *The length of development  $L_a$  and the angle of development  $\lambda_a$  of the time-like ruled surface are calculated by the following equalities:*

$$L_a = \int ds = \int \langle d\alpha, X \rangle \quad (2.4)$$

and

$$\lambda_a = \langle D, a \rangle. \quad (2.5)$$

The Steiner Rotation Vector of motion, when  $L$  is chosen as  $Sp\{T, N, B\}\alpha(s)$  in the moving space  $L/L'$  along the base curve of ruled surface given by (1.1) is obtained as

$$D = \int (k_2 T - k_1 B) ds \quad (2.6)$$

from (2.2). Where  $T$  and  $B$  are unit space-like tangent and time-like binormal vector fields at the base curve respectively  $k_1$  and  $k_2$  are also curvature functions of the base curve. The moving straight line  $X$  such that it is strictly connected to the system  $\{T, N, B\}$  is represented uniquely with respect to this system as in the form

$$X = x_1 T + x_2 N + x_3 B \quad (2.7)$$

where the components  $x_i$ , ( $i=1,2,3$ ) are scalars in  $L$ . The angle of development and the length of the time-like ruled surface which is drawn by the straight line  $X$  in  $L'$  are obtained as in the form

$$\lambda_x = x_1 \lambda_T + x_3 \lambda_B \quad (2.8)$$

and

$$L_x = x_1 L_T, \quad (2.9)$$

where  $\lambda_T$  and  $\lambda_B$  are the angles of development in the direction of the tangent and binormal of ruled surface and  $L_T$  is also the length of development in the direction of the tangent vector. When this time-like ruled surface is developable,  $P_x = 0$  by lemma 1. For this reason, we state the following theorem.

**Theorem 2.1.** *During the one-parameter motion  $L/L'$  the time-like ruled surface in the fixed space  $L'$  generated by fixed  $X$  of the moving space  $L$  is developable if and only if  $\alpha(s)$  is a helix such that the harmonic curvature of the base curve  $\alpha(s)$  of its development invariants satisfies the equality*

$$\frac{k_1}{k_2} = \frac{-(L_T^2 + L_x^2) \lambda_B}{L_x (L_T \lambda_x - \lambda_T L_x)} \quad (2.10)$$

(1.3), (1.5), (2.1) and (2.7) equalities can obtained following theorem.

**Theorem 2.2.** *The parameters of distribution  $P_N$  and  $P_B$  of time-like ruled surface drawn in  $L'$  by the corresponding straight lines to the principle space-like normal  $\bar{N}$  and time-like binormal  $B$  are obtained as,*

$$P_N = \frac{-k_2}{k_1^2 - k_2^2}, \quad P_B = -\frac{1}{k_2}, \quad (2.11)$$

respectively.

### 3. The mean curvature of developable time-like ruled surface.

If  $L$  is chosen as  $Sp\{T, N, B\}$  in the motion of space  $L/L'$  with one parameter which draws the time-like ruled surface  $\varphi(s, v)$  thus (1.1) is expressed as

$$\varphi(s, v) = \alpha(s) + v(x_1 T + x_2 N + x_3 B). \quad (3.1)$$

Let us calculate the mean curvature of time-like ruled surface which is drawn by the straight line  $X$  in  $L'$  given by the following relation:

$$2H_a = (EN + GL - 2MF) / (EG - F^2), [4] \quad (3.2)$$

where  $E, F, G$  and  $L, N, M$  are the coefficients of the first and second fundamental forms, respectively. These coefficients are obtained by partial differentiation of (3.1) according to  $s$  and  $v$  as in the form

$$E = \langle \varphi_s, \varphi_s \rangle = v^2 (x_3 k_1 + x_1 k_2)^2 + v^2 (k_2^2 - k_1^2) + 1 - 2vx_2 k_1,$$

$$F = \langle \varphi_s, \varphi_v \rangle = x_1,$$

$$G = \langle \varphi_v, \varphi_v \rangle = -1,$$

$$M = \langle \varphi_{sv}, n \rangle = \frac{-k_2 - x_1 (x_3 k_1 + x_1 k_2)}{\|\varphi_s \wedge \varphi_v\|},$$

$$N = \langle \varphi_{vv}, n \rangle = 0,$$

$$L = \langle \varphi_{ss}, n \rangle = \left\{ (x_3 k_1 + x_1 k_2) \left[ -v^2 (x_1 k_2 + x_3 k_1)^2 + v^2 (k_1^2 - k_2^2) + 2vx_2 k_1 \right] - x_3 k_1 + \right.$$

$$+ vk_2^1 \left( 1 + x_1 \left( x_3 \frac{k_1}{k_2} + x_1 \right) - v^2 x_2 (k_1' k_2 - k_1 k_2') \right) / \|\varphi_s \wedge \varphi_v\|,$$

$$n = (\varphi_s \wedge \varphi_v) / \|\varphi_s \wedge \varphi_v\| \quad (3.3)$$

is the normal of the time-like ruled surface. Let us substitute (3.3) in (3.2) and do the necessary calculations. If  $x_1$  and  $x_3$  are calculated by (2.8) and (2.9),  $k_1$  and  $k_2$  are calculated by (2.11) and  $k_1/k_2$  is calculated by (2.10) and substituted in terms of development invariants of the time-like ruled surface in (3.2) mentioned above, then

$$H_a = -\frac{L_T}{2L_X P_B \|\varphi_s \wedge \varphi_v\|}. \quad (3.4)$$

Thus the mean curvature  $H_a$  of the time-like ruled surface was obtained in terms of development invariants of the surface. The following theorem may be given as consequence of this:

**Theorem 3.1.** *In the motion of space  $L/L'$  with one parameter defined along the space-like curve  $\alpha: I \rightarrow R_1^3$  the mean curvature of the developable time-like ruled surface drawn in the fixed space  $L'$  by the fixed straight line  $X$  in the moving space  $L$  is*

$$H_a = -\frac{L_T}{2L_X P_B \|\varphi_s \wedge \varphi_v\|},$$

where  $L_T$  and  $L_X$  are length of development of the time-like ruled surface in the direction of the tangent line  $T$  and the straight line  $X$ , respectively.  $P_B$  and  $P_N$  are also parameters of distribution in the direction of the binormal and the normal.

**Definition 3.1.** *The surface is called minimal if its mean curvature is equal to zero [5].*

This definition implies that  $L_T = 0$  in (3.4).  $L_T = \int ds$  by (2.4).  $s = \text{constant}$  is obtained by the last two equalities. Since the striction curve is a point then the time-like ruled surface is a come. The following theorem may be given as a consequence of this.

**Theorem 3.2.** *In the motion of space  $L/L'$  which is defined along a space-like curve in  $R_1^3$ , the developable time-like ruled surface drawn in  $L'$  is minimal if it is a come.*

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